UNCRASHED : 1~2 DRL: 3~4 DCL: 4~5 TRYP FPV : 5~6 AIDroneSim: 6~7 FPV LOGIC : 7~8 Liftoff: 8~9 Freerider: 9~10 SkyDive: 10~11 FPV Worldwide: 12~13 FPV Battleground:13~14

UNCRASHED emulator software settings

After opening the computer software, switch between Chinese and English display in the bottom right corner of the interface, and configure the controller channel in the

"Options".



Enter the calibration interface, take the left throttle as an example, click on the guidance mode, select mode2, and

proceed to the next step. Follow the instructions to complete the debugging. If using the right hand throttle, select mode 1.



The debugging is completed as shown in the following figure.

Axis 5-8 can select the corresponding function according to

Options	Drone controls	
	RC-Controller Unknown STARTRC	*
	Throttle	
	Roll Axis1 × Auto	
	Pitch Axis2 × Intel Auto	
Controls	Vaw Axis4 × Meet Auto	
Graphics Gameplay / Audio	Reset Axis5 - X more Auto Stick calibration Desdrone : 0	
Rates	Save location Axis6 + × Auto	
Drone settings	Flight Mode Axis7 - X International Auto Reset controller settings	
	Arm/Disarm Arise × Arm/	
	Keyboard	
	Reset (key) R	None
	Save spawn location (key)	
Back		激活 Windows
Quit to Desktop		🙃 💁 🎬

preferences

DRL simulator software settings

Enter the simulator and click on STARTRC below



Click on automatic calibration and debug according to the

instructions

OME > CALIBRATION MENU			- DRL <u>S//</u> 4.2ee16.rte-w
	CALIBRATION MODE	FINE-TUNE MODE	
	MANUAL CALIBRATION		
	QUICK CALIBRATION	CHANNEL SELECTION	
	SELECTING A CALIBRATION OPTION WILL OVERWRITE ANY SAVED PROFILE FOR SELECTED CONTROLLER	THESE OPTIONS ALLOW TO FIRE TUNE THE CALIBRATION AND ARE AVAILABLE ONLY FOR ALREADY CALIBRATED CONTROLLERS	
	STARTRC \$		SENSITIVITY
баск		a c	HELP)
			撤回 Windows 期间 gruppa Windows

Taking the left-hand throttle as an example, after setting it up, it is shown in the following figure

HOME > CALIBRATION MENU							- ORL <u>SIM</u> 4.2.ee16.rts-win
	THROTTLE	MID-STICK X INVERT X	RESET	PITCH	INVER		
	MIN	MID	MAX	MIN	MID	MAX	
	O THROTTLE				016 🗹		
			RESET			RESET	
BACK		0%			0%		SAVE
					-3.JE		
							湖江드 Windows 유민 대한 Valley Windows,

DCL simulator software settings

Open the DCL emulator software on the computer, click on the "Settings" and "Control" buttons, and enter the STARTRC S8 joystick settings. In the settings interface, click on "transmitter calibration" to enter the corresponding calibration

page.





The corresponding channel allocation should be executed according to the diagram. If there is a problem with the joystick not returning to the center, you can follow the prompts in the "Calibration End and Return to Center" area on the right to complete the calibration.

TRYP FPV Simulator Software Settings Open the computer emulator software and click on "Control" in "Options"



After calibrating the left throttle, the following settings can be

made

¥ 📴 🗶 🖳 🖣	CONTROLS SE	TTINGS			TILYP
	SELECTED MODEL:	STARTRC		Mode2	-
THROTTLE BIND AXES	Axis 2 (
COLL BIND AXES	Axis 0	INVERT DEADZONE			8
JAW BIND AXES	Axis 3	INVERT DEADZONE	.05 \$		F
	Axis 1	INVERT DEADZONE 🚺			
ABRYSJUTYJWI TIQENMAR ACTO	nit T THEOTICGAT Som Mation NEODE 0.5		2 SETUP GUIDE	CALIBRATE	
INPUTS You can assign your RC switches	s to any function.			RESET INPUTS	
22 -22		Respawn / Restart	R	Controller Button 1	1000
		Add Camera Angle	Up	Controller Button 11	
and the state of	7	Sub Camora Anglo	Down	Controller Button 17	Windows RECORD Wodows

AIDroneSimulator software settings

Open the computer emulator software and click on the

"Controller" button on the left



Taking the left hand throttle as an example, select "Mode 2" and set it sequentially at the controller shaft. After setting, confirm that the channel is reversed without any abnormalities, as shown in the following figure



		0 487	• 500 Di	splay : ∢ Mode 2 ▶		Ì	
	USB Input Value	Flight Controller Axis Value	Controller Axis	Inversed ? Dead zone	Min Mid	Max	Auto
Throttle	0	0	GENERICUSBCONTROLLER AXIS 6		0 0 500 0	1000 0	AUTO
Roll	500	5 00	GENERICUSBCONTROLLER AXIS 8	0 .	0 🕫 500 🕫	1000 🕫	AUTO
Pitch	500	5 00	GENERICUSBCONTROLLER AXIS 7	0	0 🔹 500 🔹	1000 -	AUTO
Yaw	500	487	GENERICUSBCONTROLLER AXIS 5	0 .	80 0 511 0	946 🗳	AUTO
74	Thy	- Aller					
		est est	5 I M			波话 Windows Horizan Land W	RETUR

FPV LOGIC Simulator Software Settings

Open the computer emulator software and click on "Controller"

in the bottom right corner



Taking the left-hand throttle as an example, set AXIS-1 for ROLL, AXIS-2 for PITCH, AXIS-4 for YAW, and AXIS-3 for THOTTLE. Set the channel in reverse as shown in the following figure

CON Controller :	ITROLLER SETUP		1
O:STARTRC	· · · · · ·	AXES BUTTONS AXE-4 -0.001 AXE-4 fer root 1 2 3 4 AXE-4 -0.001 AXE-5 for root	
ROLL	AXIS-1	AM563 GOT AM564 Into [cput B 6 7 8 AM564 GOT AM564 Ma [rept] 0 10 12 12 AM564 GOT AM5765 Into [rept] 0 10 12 12 AM564 GOTO AM5765 Into [rept] 13 14 15 16 AM567 GOTO AM566 Into [rept] 13 14 15 16 AM567 GOTO AM566 Into [rept] 17 18 19 20	1
PITCH	-D AXIS-2 - AUTO	INPUT STATUS	
YAW	AXIS-4	RESET SLOW MOTION ACRO FPV ANGLE CONTINUE FUIGHT MODE CAMERA MODE	5
THROTTLE	AXIS-3		1
RESET	AXIS-6 AUTO		
SLOW MOTION	AXIS-7		
CAMERA	AXIS-5 Button Invert Deadzone X	CALIBRATION	
FLIGHT MODE	AXIS-8 Button Invert Deadzone X	RESET CALIBRATION DATA	1.0
BACK		SAVE	The Windows Frint Ban Watch Windows,

Liftoff Simulator Software Settings

Open the emulator software on the computer and click on the Controllable button in OPTIONS to set up the remote control



Click CALIBRATE to set the remote control, and then

follow the instructions to set the throttle. If the small aircraft on the left cannot fly normally, reset it





Freerider emulator software settings

Open the computer emulator software and click on Calibrate Controller to set up the emulator



Center the control lever and click OK, then proceed to adjust

each joystick according to the guidance

Center all sticks	
- 0	
OK.	Skip to trim settings

SkyDive Simulator Software Settings

Open the computer emulator software, click on the bottom right corner to enable CALIBRATE for calibration



Click on 'Click to Assign' and move the corresponding remote sensor. Set the left throttle as shown in the figure

Controller Calibration		Configure		Controller Calibration	
Throttle Stick Mode					
	٢	FPV Radio	, ,	Controller Calibration helps ensure that your controller is properly detected by the game and provides accurate control. This involves moving each stick to the end positions, so the game can	
Throttle		- 2	Axis 2	detect the full range of motion of the sticks.	
Yaw	_	- 2	Axis 3	standard controllers like FPV Radios, as they are not automatically recognized, which is why this option is disabled for gamepad users.	
Pitch	417	- 2	Axis O		
Roll	1517	- =	Axis 1 🕅		
Arm	_	- +	Click to Assign 🔗		
Flight Mode	_	⇒ ⇒	Click to Assign 🔗	- / -	

FPV Worldwide Simulator Software Settings

Open the computer emulator software, click on the settings in the bottom left corner to enter the settings interface



Click on KEY BINDINGS in Controls to set up the remote

control, and click BIND STICKS AND BUTTONS to set up

each joystick. After setting up, see the following figure

HOME SPOTS		SETTINGS	RB				00:03:1	
GAMEPLAY	AUDIO	VIDEO	CONTROLS	1				
GENERAL	EY BINDINGS							
CHOOSE YOUR CO	NTROLLER		STARTRC	•				
CONTROLLER MODE			2	•	Axis O			
	BIND STICKS	AND BUTTONS	3		Axis 1		_	
THROTTLE AXIS			2	•	Axis 2 Axis 3	Axis 2 Axis 3		
			ON		Axis 4			
YAW AXIS			3		Axis 5			
			OFF		Axis 6 Axis 7			
YAW INVERTISTIC	ĸ							
PITCH AXIS					Throttle			
PITCH INVERT STIC	CK		OFF	•	Yaw			
ROLL AXIS		4	1	•	Pitch			
ROLL INVERT STICK			OFF Boost					
BOOST AXIS			6	•	Reset			
BOOST INVERT ST	ICK		OFF	•				
RESET AXIS		4	6	•				
RESET INVERT STI	СК		OFF	•				
						Y APPLY Delete	RESET SETTINGS 🕑 B	ACK

FPV Battleground Simulator Software Settings

Open the computer emulator software, click on the options in

the bottom left corner to enter the settings interface



Set up each channel in controls, taking the left-hand throttle as

an example, as shown in the following figure

